

Iceberg detection with SAR using the YOLO v8 deep learning model

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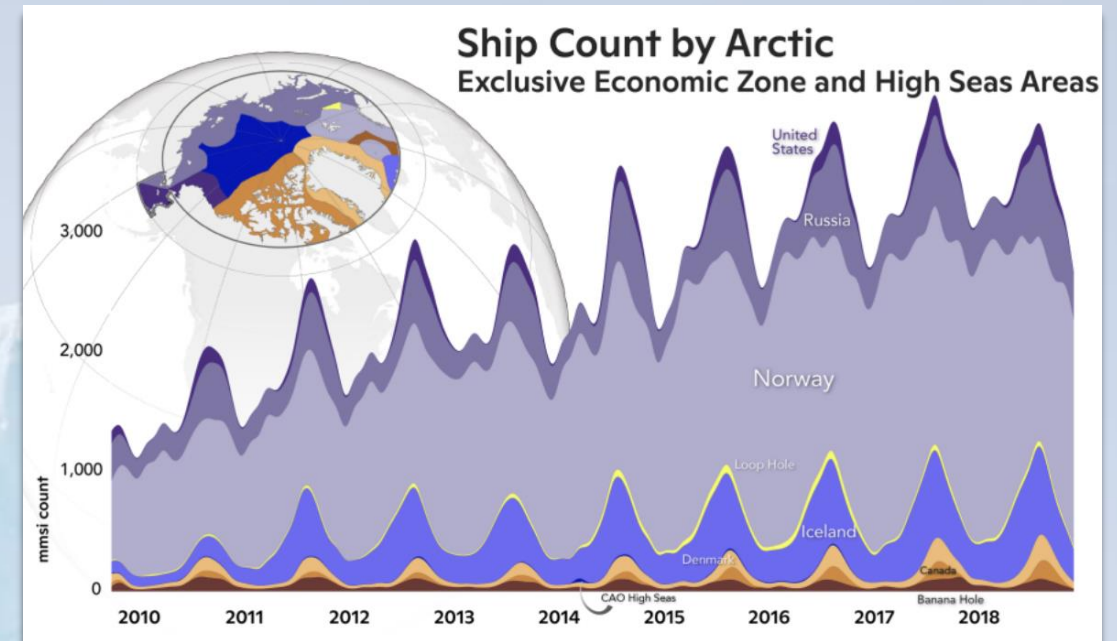
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Context:

- By lowering the quantity of ice present, climate change is enabling increased Arctic shipping.
- Iceberg collisions cause extensive repair costs, environmental crises from spillages and/or even loss of life.
- 2-3 iceberg-ship incidents a year in the Northern Hemisphere, despite the modern radar technology on board ships.
- A new approach to detection is considered that utilises a state-of-the-art deep learning model.

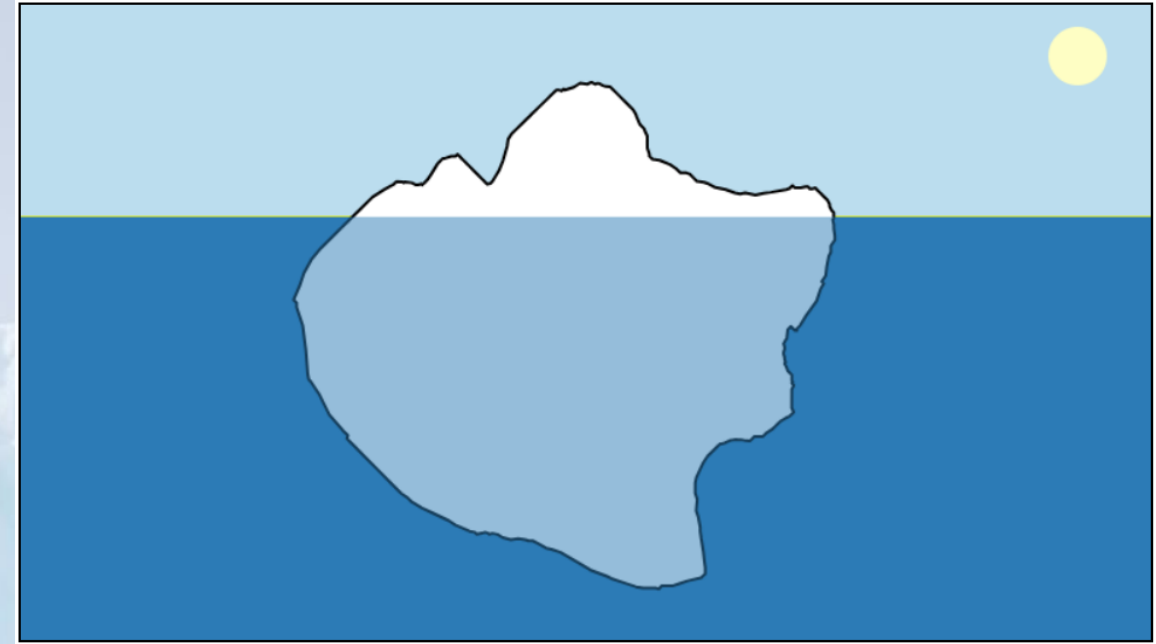
Icebergs are **hazards** to ocean activities. They are essential to monitor.



Sinking of MS Explorer, 2007

An introduction to icebergs:

- Icebergs are pieces of freshwater ice broken from a glacier tongue or an ice shelf.
- They can drift into open water, or become embedded within sea ice floes.
- They are classified by both size, and by shape, although this is based on in-situ observations.
- Iceberg detection is an important field, with importance raised due to Titanic.
- Only about 11% of an iceberg is visible above the ocean surface.



Iceberg physics can be fun!

Icebergs can topple over as well as drift. Tracking and monitoring is essential.

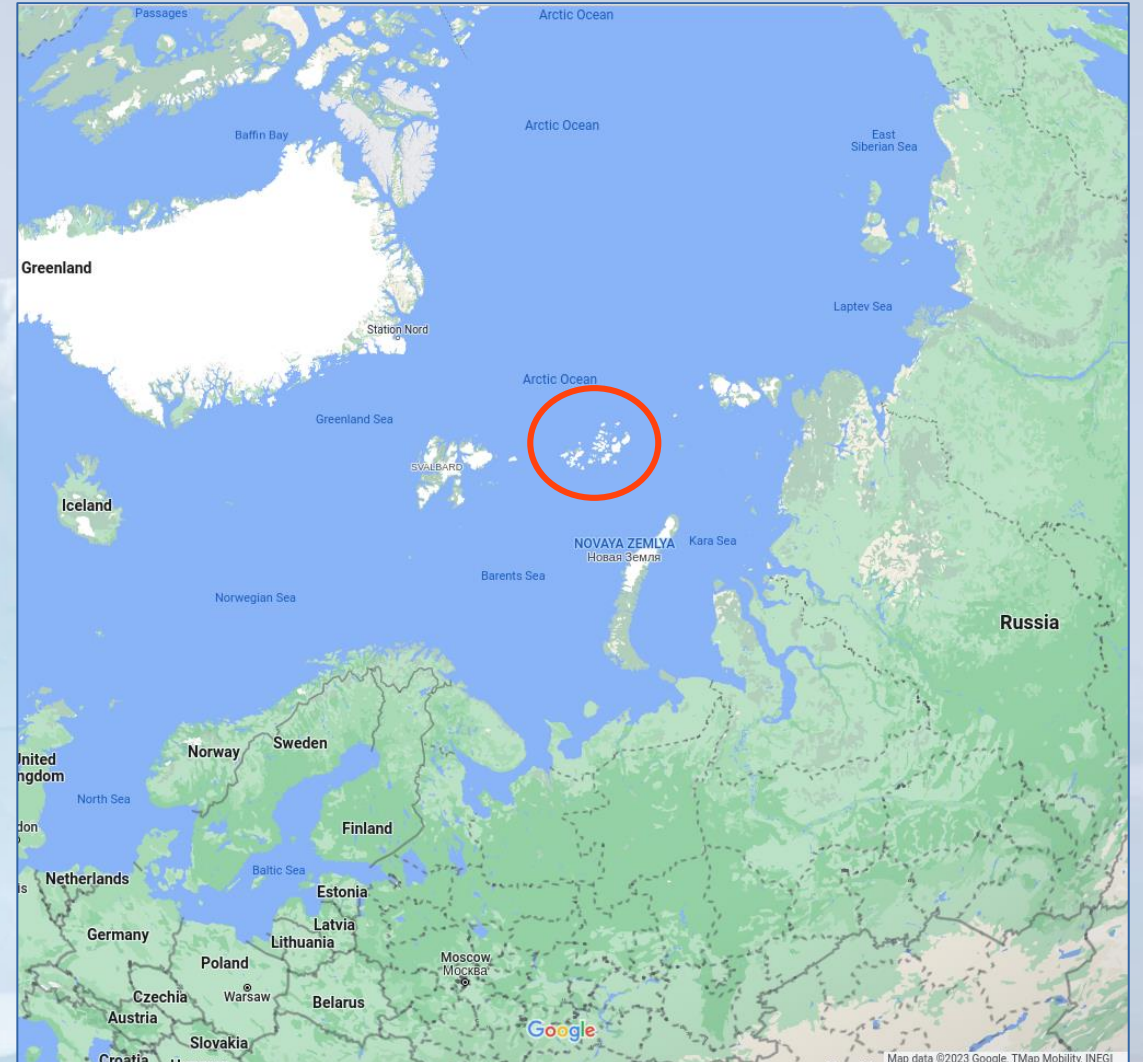
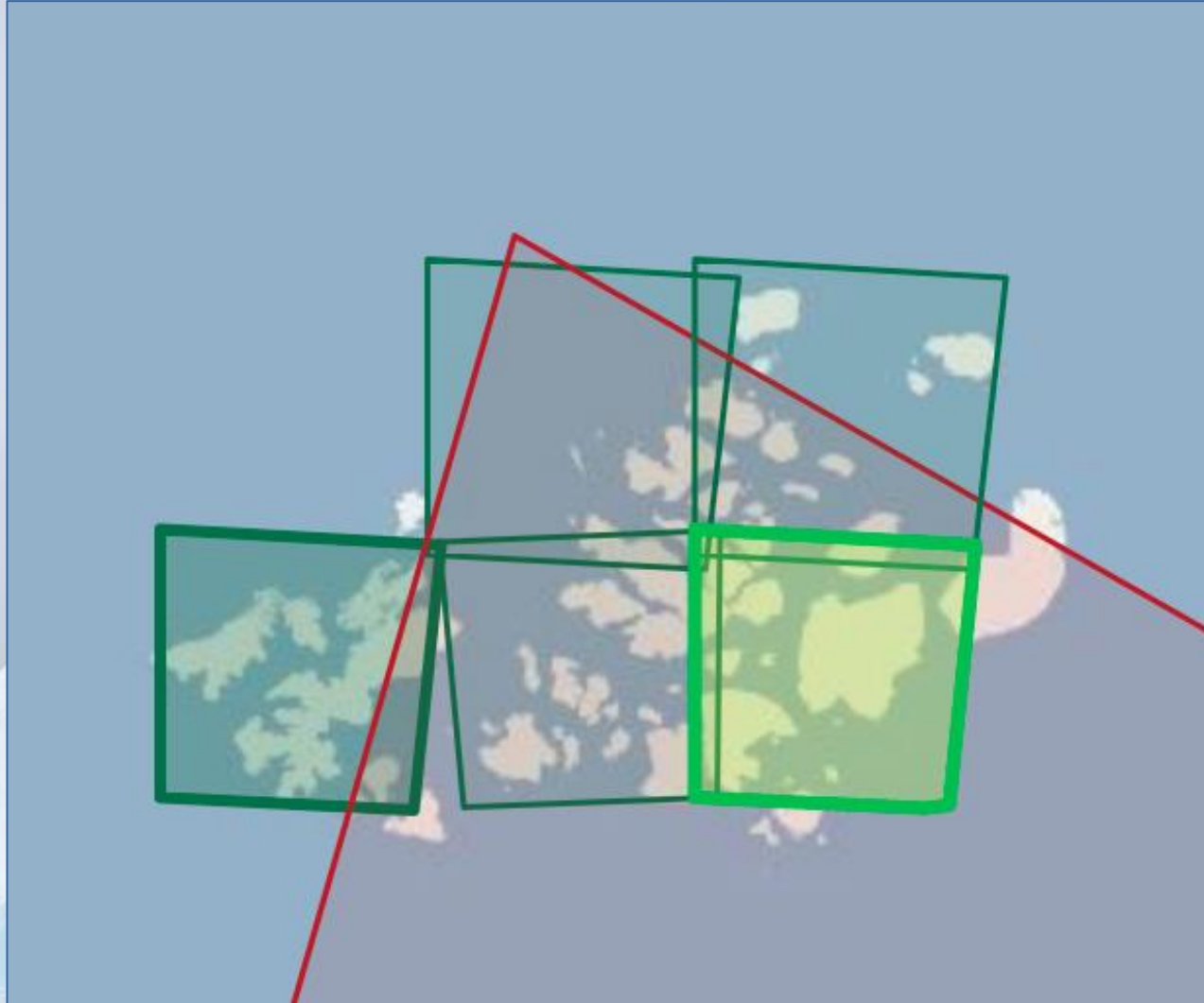
Joshdata.me/iceberger.html

Aside:

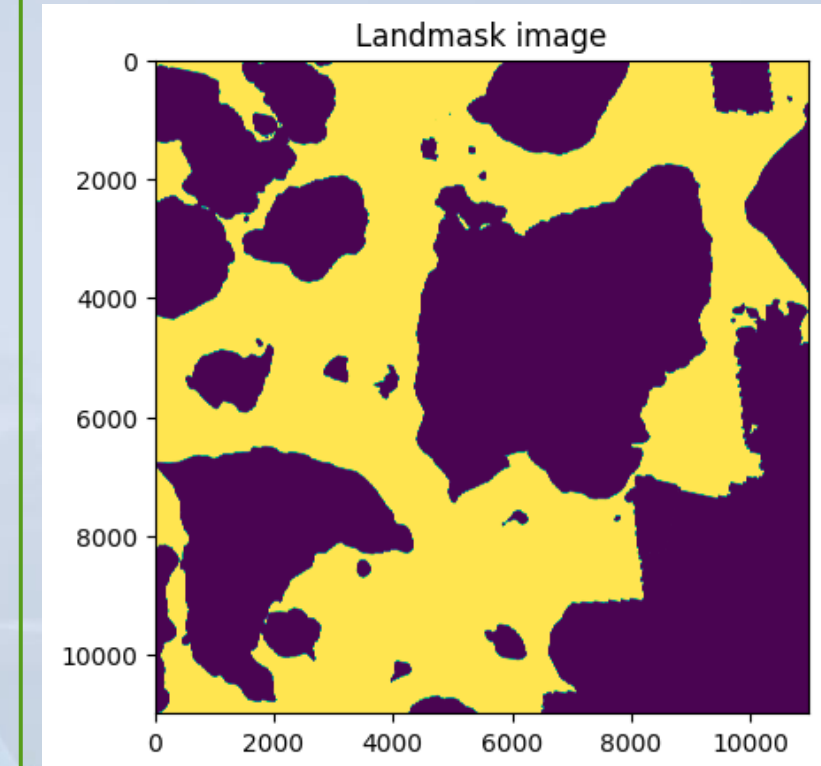
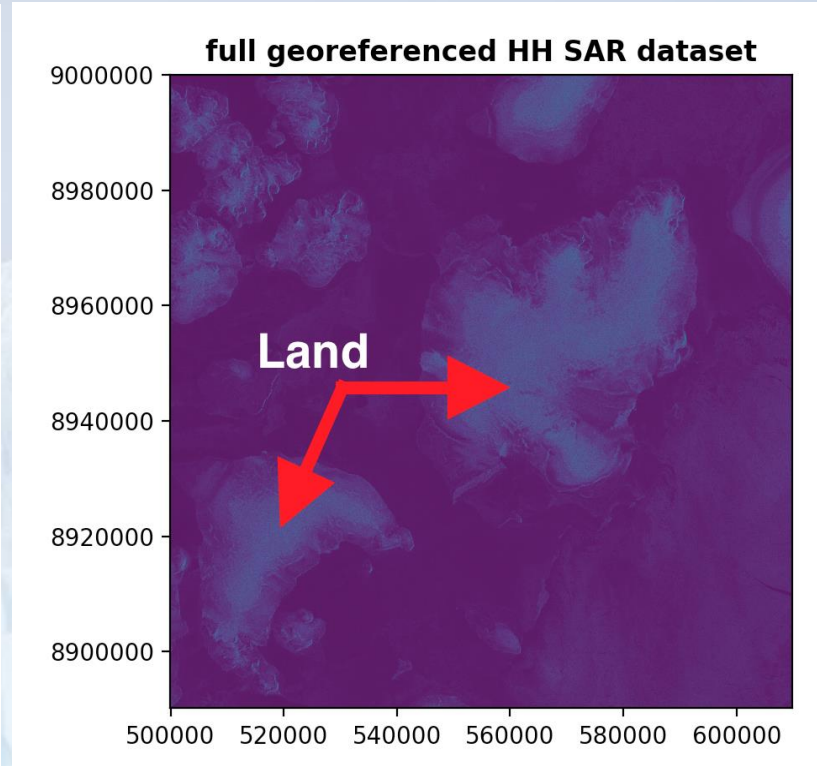
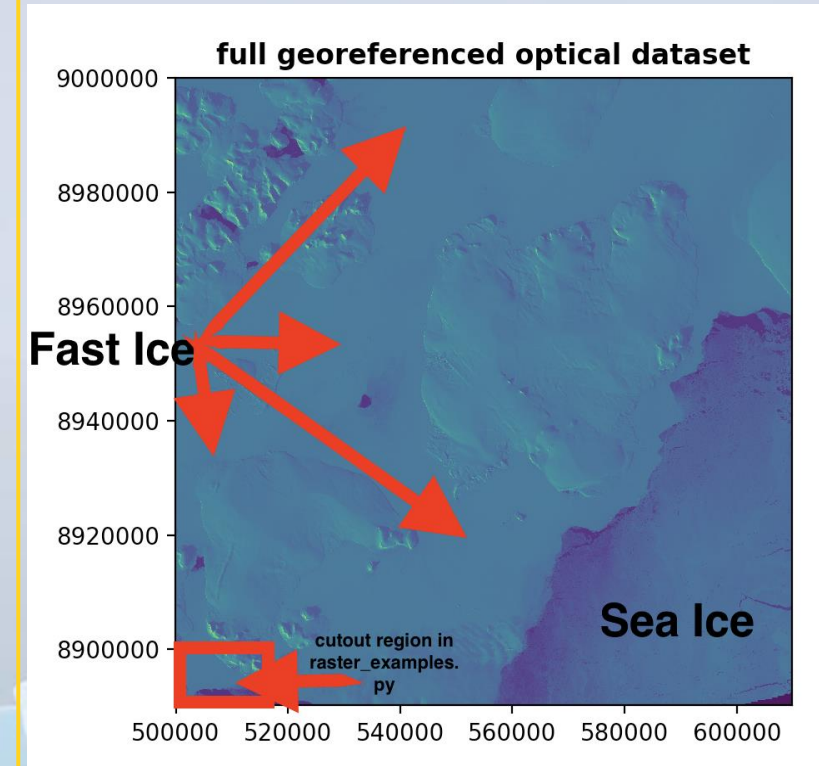
- This idea came from wanting to apply a machine learning algorithm we had developed for astrophysics to problems here on Earth.
- We were using it to find the most massive objects in the Universe: Galaxy Clusters.



Franz Josef Land (FJL) in the Arctic:



Fast ice, sea ice and land in FJL:



Synthetic-aperture radar (SAR) and optical image data from European Space Agency (ESA) Sentinel 1 & 2 satellites (~100km on the side)

Landmask image data from the Polar Geospatial Center

Problem:

We cannot easily separate icebergs from sea ice, due to similar SAR signatures.

We need an algorithm of some sort to discriminate such a target.

Solution:

The dual polarisation intensity ratio anomaly detector:

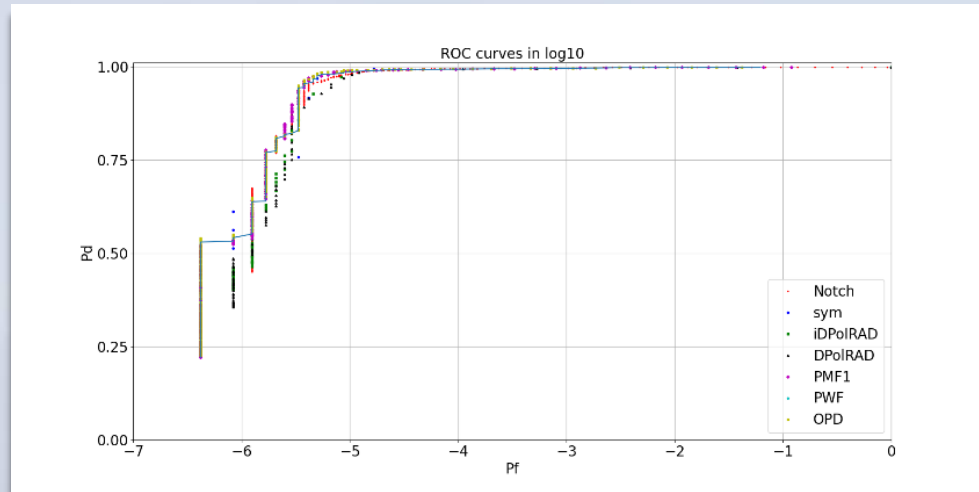
$$I = \frac{\langle |VH|^2 \rangle_{test} - \langle |VH|^2 \rangle_{train}}{\langle |VV|^2 \rangle_{train}} \sigma^0_{HV} = \Lambda \sigma^0_{HV} > T_{\Lambda}$$

We can utilise the cross polarised SAR image for stronger iceberg backscatter.

But after we have the final image, we need a way to quantify the performance.

We could:

Use ROC curves, with or without a Constant False Alarm Rate (CFAR) method to find the most optimal performance.



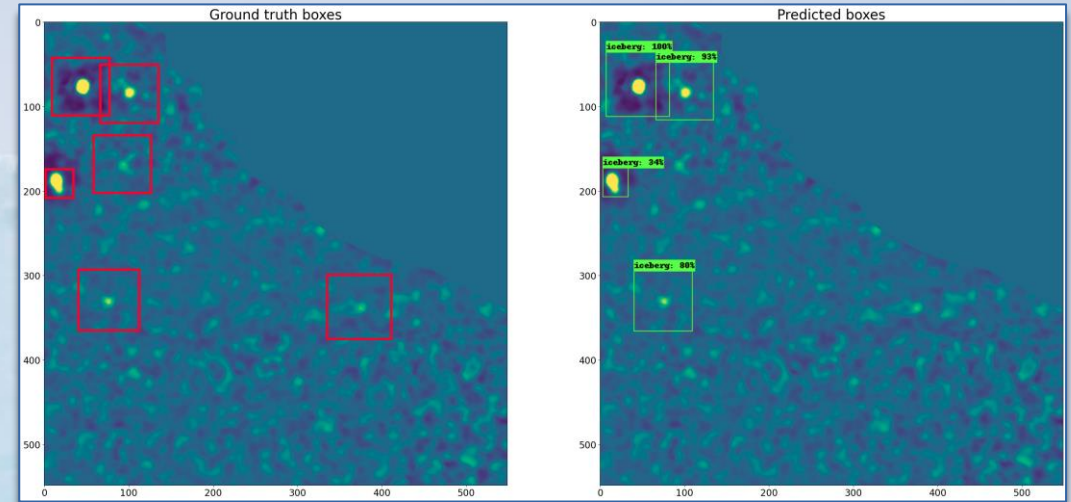
But:

CFAR requires a probability density function (pdf) representing the single intensity.

For real world detection, ideally we want a more automated process with lots of data.

This is where deep learning comes in:

Computer vision can be used to identify icebergs. This would involve training a model to draw bounding boxes around icebergs.

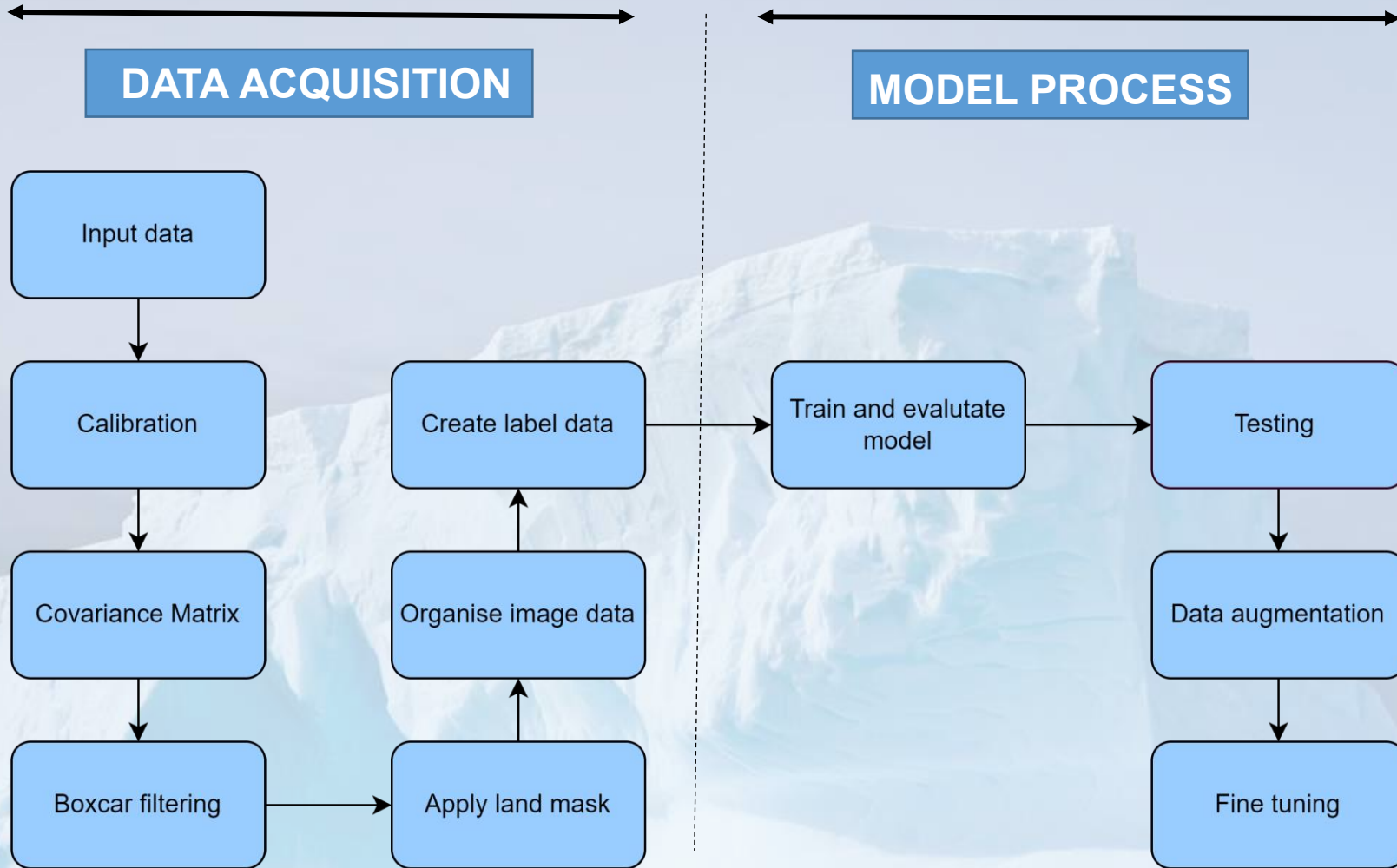


Past work:

Faster RCNN model was used to perform object detection in land-masked Sentinel-1 images of icebergs in Franz-Josef Land.

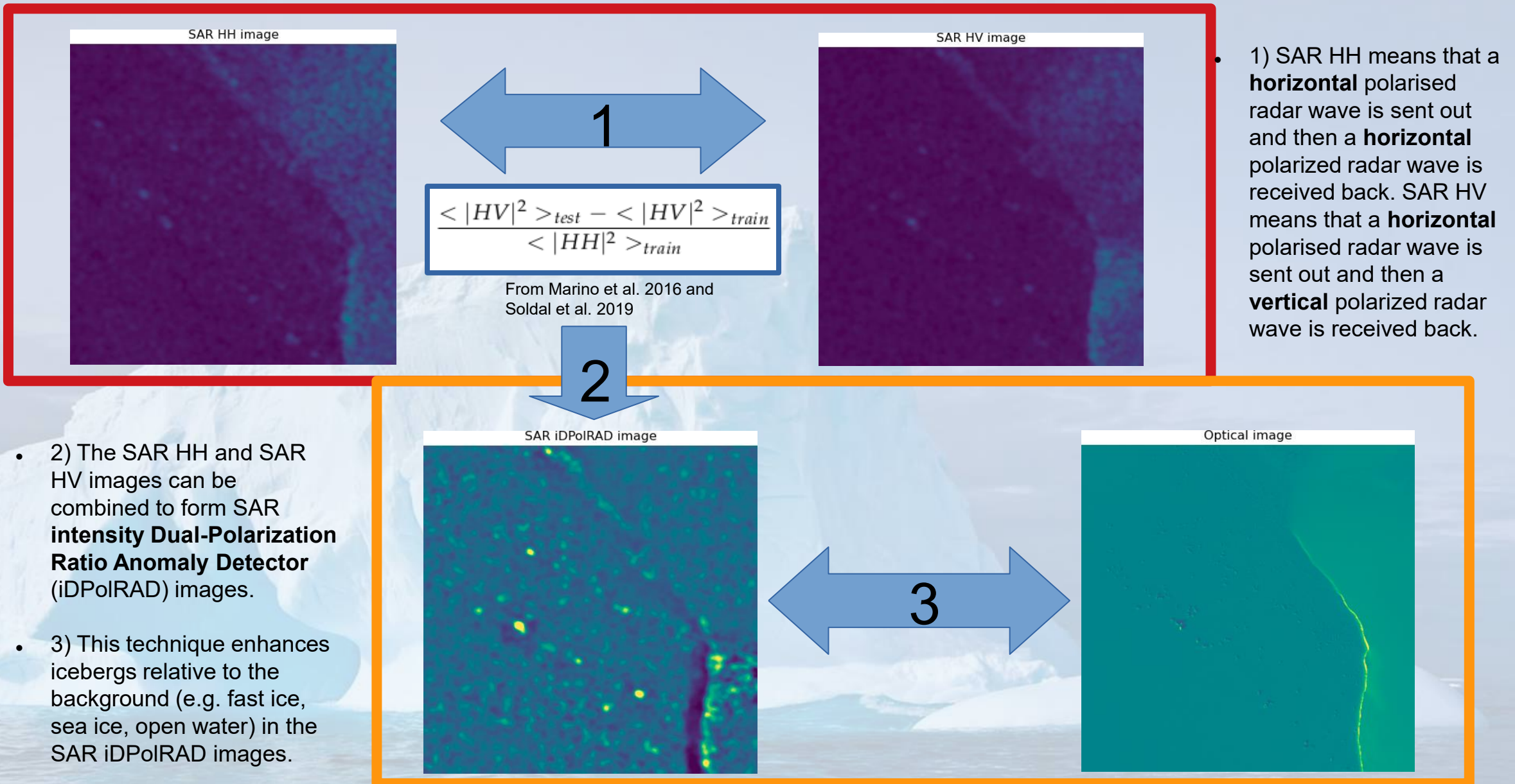
My project has expanded upon this using YOLO v8.

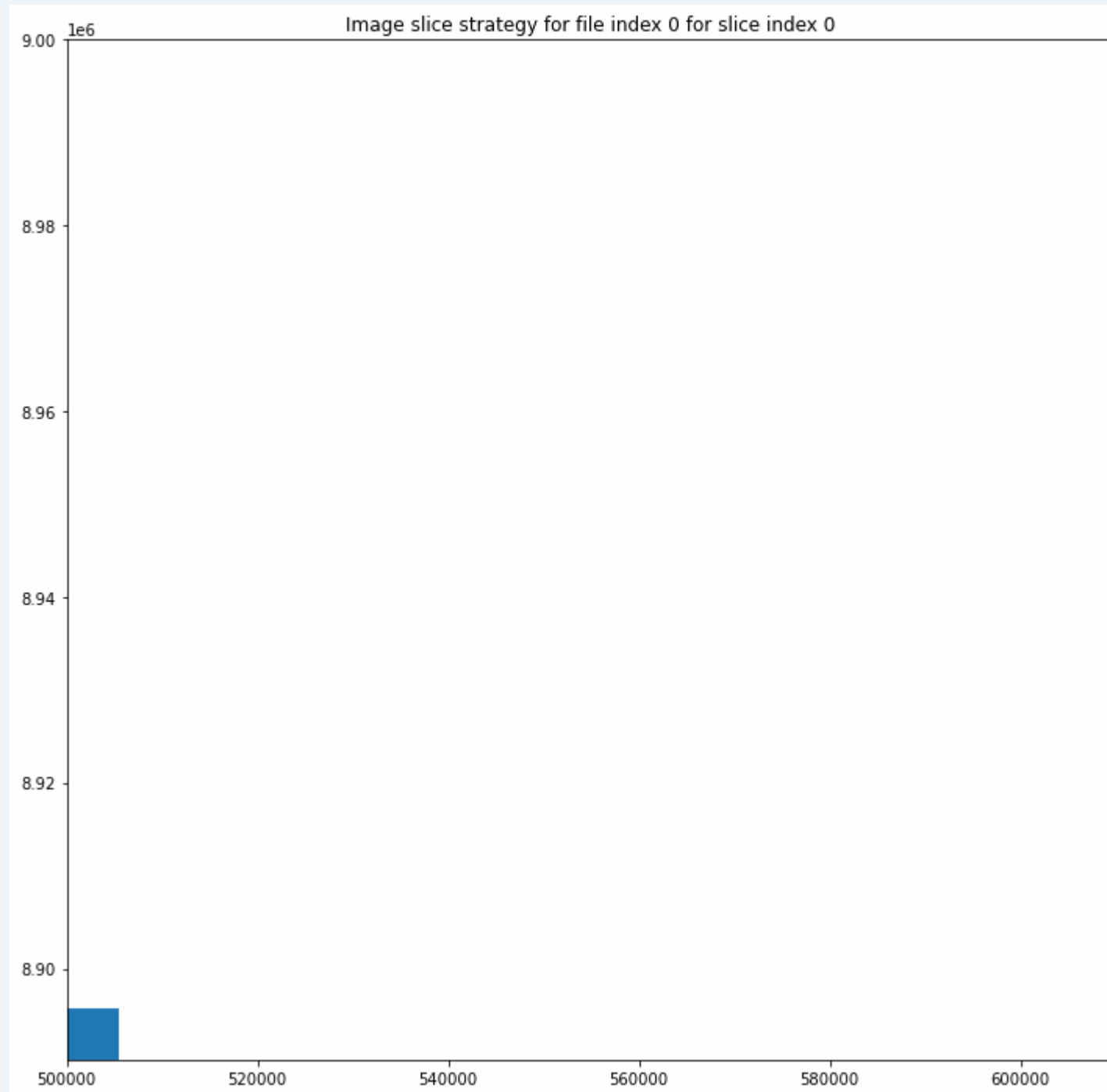
Methodology of current work:



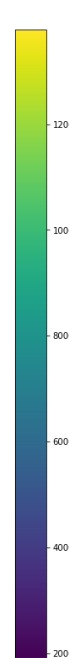
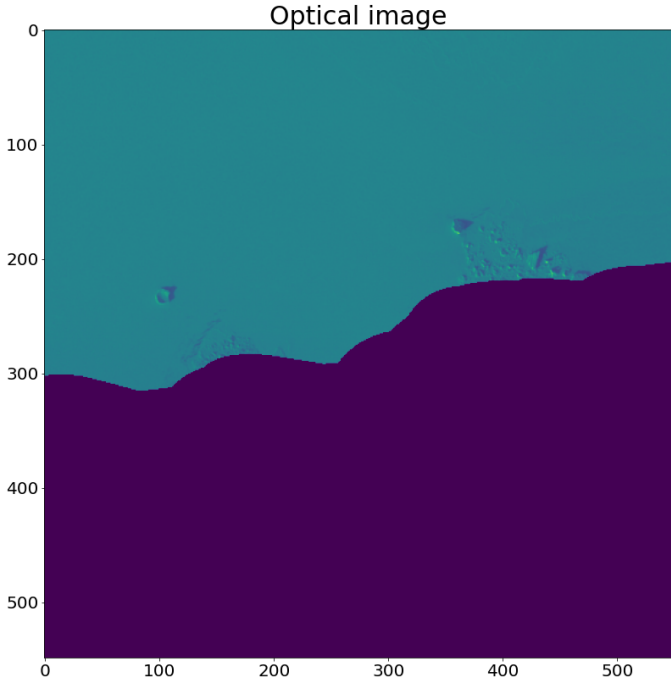
- The previous model only used 104 images each with icebergs.
- This work has utilised data augmentation to produce more data for the model.
- The next step is tweaking the hyperparameters and then evaluating the subsequent performance.
- This required multiple trainings and tests.

Image data processing:

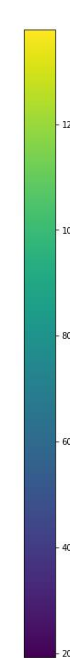
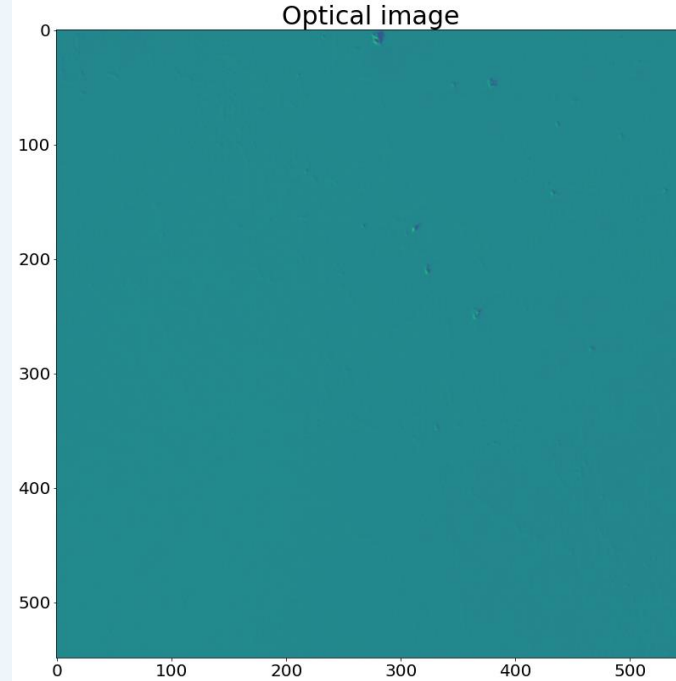




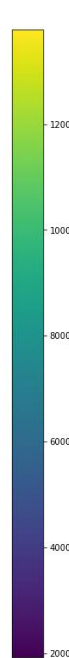
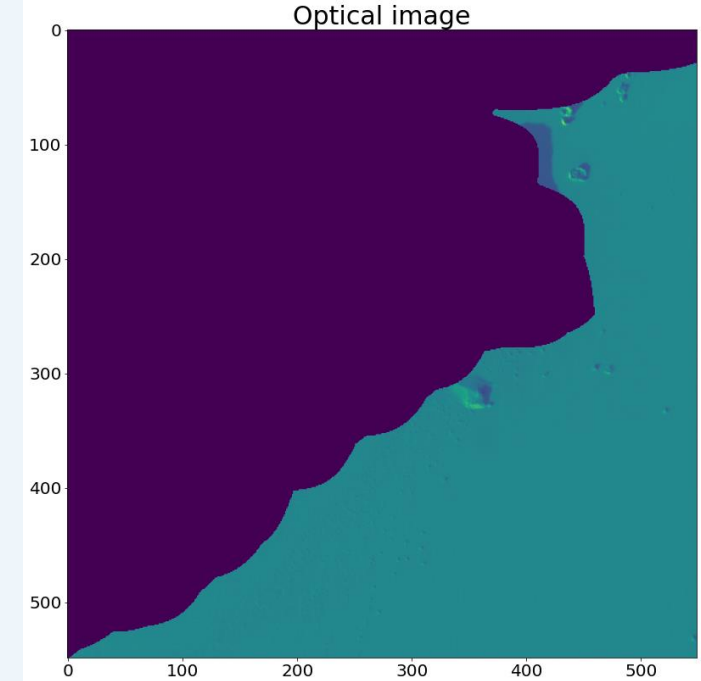
Optical image



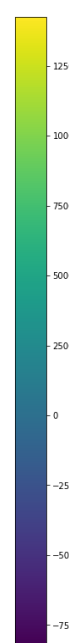
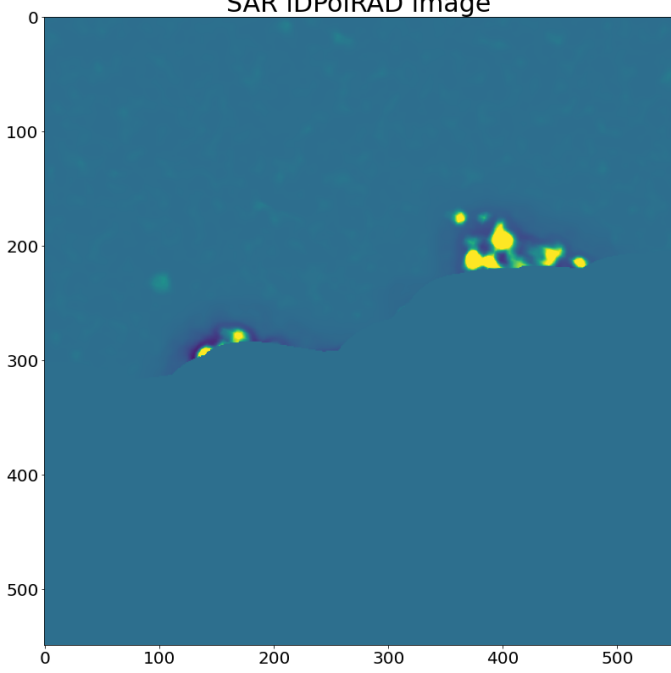
Optical image



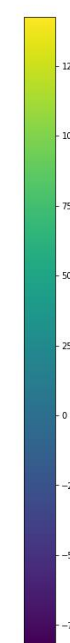
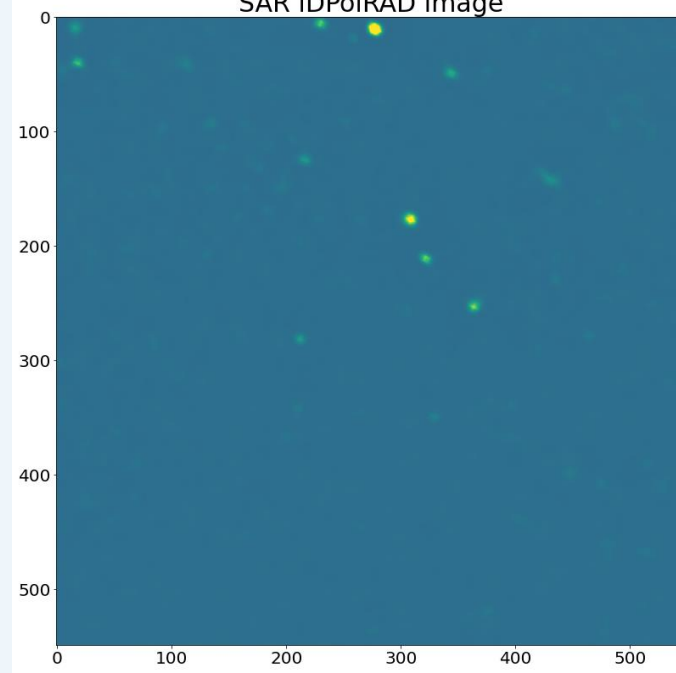
Optical image



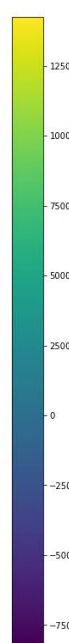
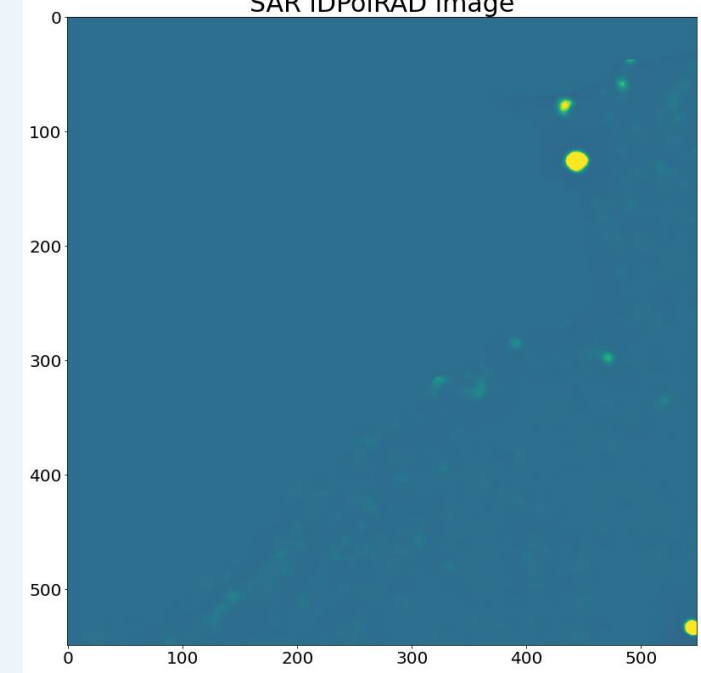
SAR iDPolRAD image



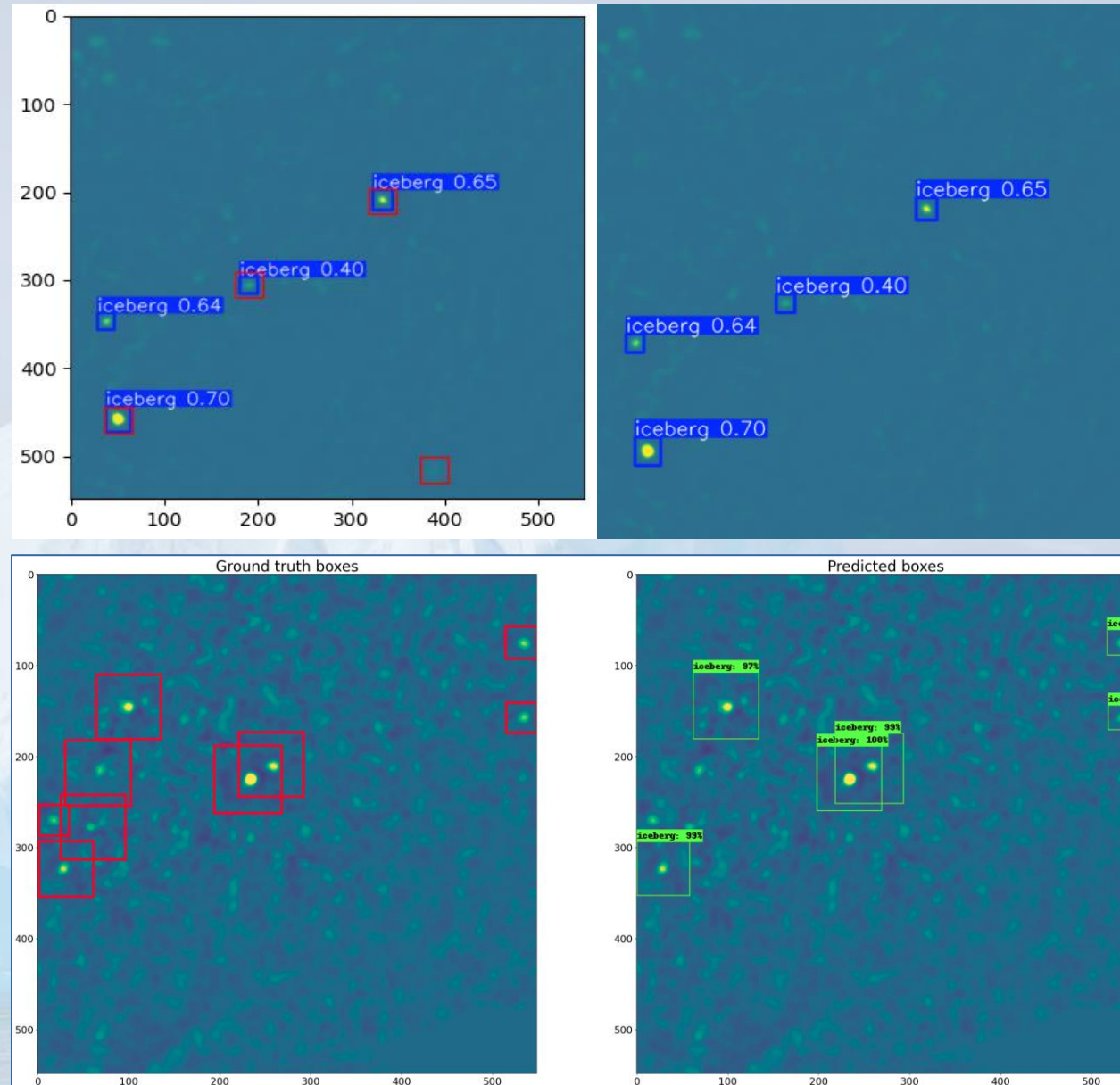
SAR iDPolRAD image



SAR iDPolRAD image



Example of predictions made by the models during testing:

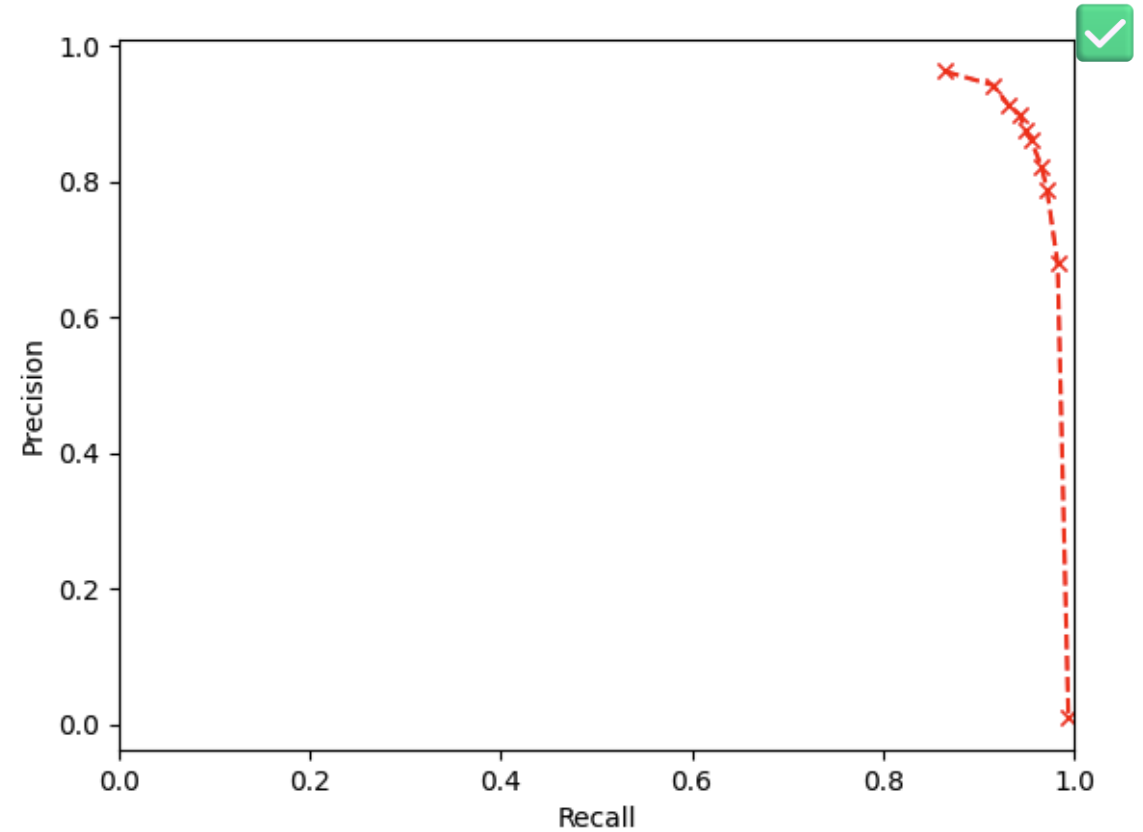


Performance:

$$Precision = \frac{TP}{TP + FP}$$

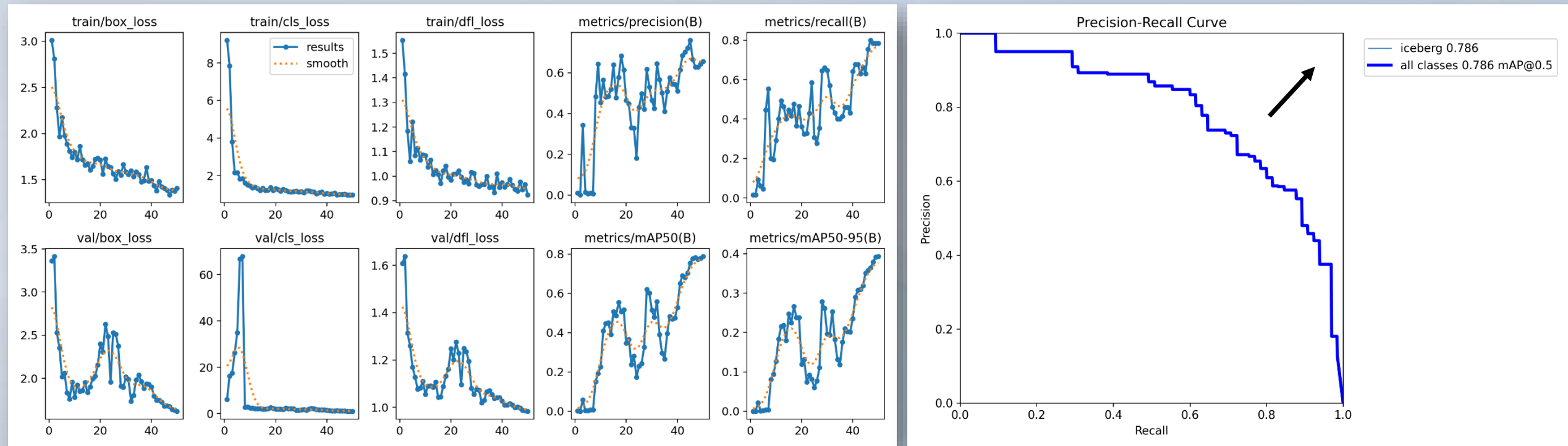
$$Recall = \frac{TP}{TP + FN}$$

$$F1 - score = 2 \times \frac{Precision \times Recall}{Precision + Recall}$$



- Precision recall and F1 score, each point on graph represents a threshold of confidence in objects being icebergs.

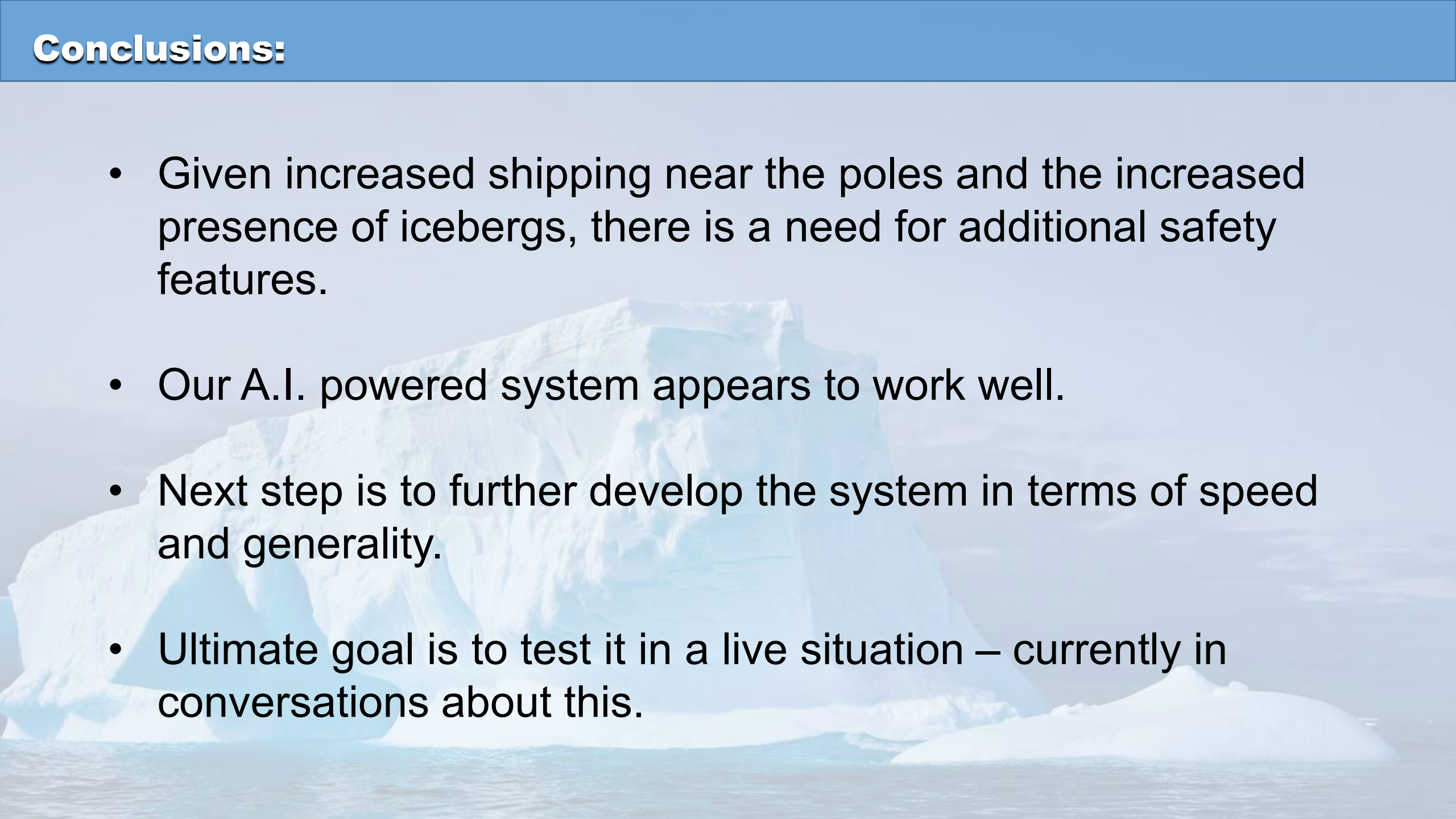
Initial results of YOLO v8 model:



- Initial results suggest no overfitting.
- Model was trained for 50 epochs.

- A precision of ~ 0.8 with a Recall of ~ 0.8 .
- Aim is to find the highest Precision and Recall (top right corner).

Conclusions:

- Given increased shipping near the poles and the increased presence of icebergs, there is a need for additional safety features.
 - Our A.I. powered system appears to work well.
 - Next step is to further develop the system in terms of speed and generality.
 - Ultimate goal is to test it in a live situation – currently in conversations about this.
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- A large, jagged iceberg floats in a calm, blue-grey sea. The iceberg's surface is textured with various ridges and crevasses. In the foreground, a smaller, smoother iceberg is partially visible. The background shows a hazy horizon under a pale sky.